INVITED COMMENTARY

Commentary on 'A Comparison of Accuracy of Image- versus Hardwarebased Tracking Technologies in 3D Fusion in Aortic Endografting'

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Rolls et al. present an interesting paper on a new perioperative fusion imaging technology that could facilitate the endovascular treatment of complex abdominal aortic aneurysms (AAA) in the future.¹ Fusion imaging is based on merging pre-operative computed tomography (CT) angiography and intra-operative digital subtraction angiography (DSA) or fluoroscopy images to create a three dimensional (3D) mask of the aorta and its branches in order to improve accuracy of complex aortic endograft delivery, facilitate branch vessel catheterization, and at the same time reduce the amount of contrast and radiation. Initially proposed by Penney et al. in 1998,² this fusion imaging technique is based on a series of digital images reconstructed from pre-operative CT data that mimic fluoroscopic images, and referred to as digitally reconstructed radiographs (DRRs). DRR series are analyzed for pixel distribution. Pixel distribution is utilized to match the most appropriate DRR images to the live fluoroscopic images throughout the procedure and to provide the best 3D vascular mask. The authors therefore called this system "image tracking" (IMT). Based on this approach, in 2010 Carrell et al. described the initial clinical use of a fully automated, image based two dimensional/3D registration system for endovascular (EV) AAA treatment.³ The technology has been further developed and commercialized by the Cydar Medical Company (Cambridge, UK).

Rolls et al. compare the new Cydar EV system with a commercially available one from Siemens, called Hardware Tracking (HWT) because the 3D masks generated by merging pre-operative CT data with intra-operative DSA require tracking the position of the C-arm and the operating table.¹ On a consecutive series of 12 patients undergoing standard and complex EV aneurysm repair

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for AAA, Rolls et al. measured the distance between preoperative IMT and HWT "fusion" markers and the corresponding reference points (ostia of the renal arteries) on the fluoroscopy screen.¹ The aim of the study was to evaluate the overlay accuracy of both systems when an automated protocol is applied during the procedure. The authors found that the overlay was significantly (p = .001) more accurate in the IMT (median error 3.9 mm) versus the HWT (median error 8.64 mm). However, the instructions for use of the Siemens system clearly recommend manual adjustment of the overlay following any manipulation or movement of the patient, and this limitation could account for the lower accuracy of the HWT system. The study design clearly highlights one major advantage of the IMT system, which is the automated adjustment of the 3D mask. The more cumbersome manual adjustments required for the HMT could be avoided but at the price of a 10-15 s delay in order to obtain the appropriate overlay. Other major advantages of the image based fusion are the possibility of working with any type of X-ray fluoroscopy set (mobile or fixed, image intensifier, or flat panel detector) and to avoid the intra-operative cone beam CT. Unfortunately, use of the IMT system is currently limited by the extensions of the available C-arm angulations ($<30^{\circ}$ cranio-caudal and <40° anterior-oblique). Therefore, as supported by the results of this preliminary study, the image based fusion technology should be further implemented and more clinical evidence should be collected.

REFERENCES

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