

Error Characteristics of Satellite-only Global Gravity Models after Solid Earth Data Reductions

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Background

- Global satellite-only gravity models provide unparalleled spatial homogeneity in coverage and quality, at length scales suitable for lithospheric density modelling.
- Geophysical inverse problems require isolating an anomalous signal in the observed gravity field, through removal of the effect of known masses (data reduction, e.g. topography, sediments ...)
- Error characteristics of gravity models: 3 orders of magnitude smaller than reduction uncertainty at the same length scales. Data reduction and inversion parameters are the main error sources.

Forward Modelling Algorithm

We rely on the SHTOOLS [1] implementation of Wieczorek & Phillips (1998) algorithm [2] spectral forward modelling algorithm for the potential of a relief with lateral variations of density, referenced to a spherical interface.

from Wieczorek (2007) [3]

Sph. harmonics coefficients of the relief (to the n-th power)

$$(ph^n)_{lm} = \frac{1}{4} \int_{\Omega} [\rho(\theta, \phi) h^n(\theta, \phi)] Y_{lm}(\theta, \phi) d\Omega \quad \text{with } \Omega = (\theta, \phi) \quad (1)$$

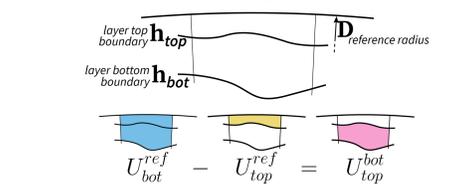
Sph. harmonics coefficients of potential

$$C_{lm} = \frac{4\pi D^3}{M(2l+1)} \sum_{n=1}^{n_{max}} \frac{(ph^n)_{lm}}{D^n n!} \frac{1}{(l+3)} \quad (2)$$

Potential (exterior to relief)

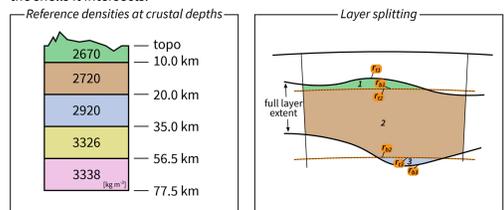
$$U(\mathbf{r}) = \frac{GM}{r} \sum_{l=0}^{l_{max}} \sum_{m=0}^l \left(\frac{R_0}{r}\right)^l C_{lm} Y_{lm}(\Omega) \quad (3)$$

We set up a layer-wise forward modelling scheme:



Density reference and layer splitting

Global density reference: adapted from AK135[4], discretized in geocentric ellipsoidal shells of constant density. The "known densities" of the modelled layers are expressed against this reference, after slicing each layer according to the shells it intersects.

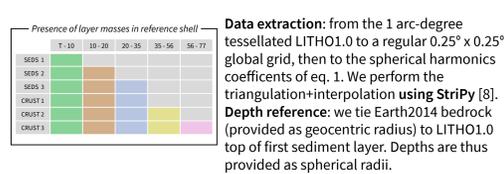


Terrain correction: input topography, water, ice

We use the Earth2014, 1 arc-min shape model [5] to obtain a terrain correction (TC). We forward modelled an ellipsoid-referenced solid topography effect, plus water and ice stripping. When this TC is removed from the observed gravity disturbance, we obtain "No Ellipsoidal Topography of Constant density" gravity disturbance (NETC, see [6]).

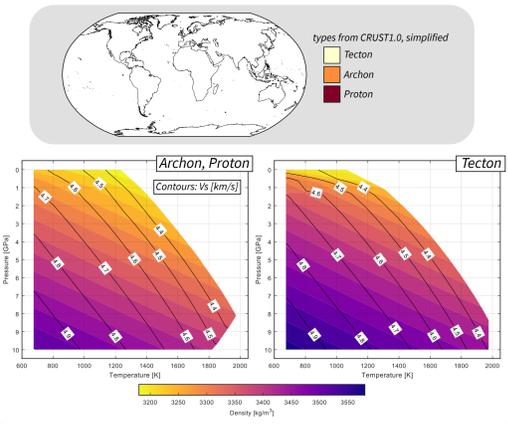
Sub-surface data: LITHO1.0 [7]

- Readily available, global depth-density model, layer defined: topography to lithosphere-asthenosphere boundary.
- Surface wave based, from an integrated starting model (multiple sources): no information on coverage and data uncertainty, this suggests caution.
- We consider it fit-for-purpose for this uncertainty-propagation test.



Lithospheric mantle: velocity-to-density conversion

- Vs to density for LITHO1.0 'LID' layer (Moho to LAB)
- density and Vs forward modelling using Perple_X [9]
- simple compositional model: Archon/Tecton, according to Griffin et al. 2009 [10]



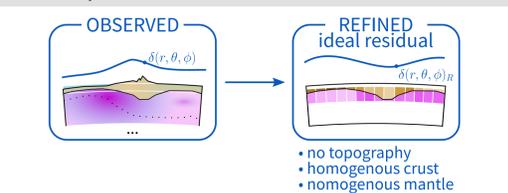
Uncertainty propagation through random modelling

- error assumptions on the input data: **depth and density**
- random modelling on 5000 independent draws
- depth uncertainty, st. dev 5% of depth
- density uncertainty, st. dev 100 kg m⁻³
- simple error criteria (realistic, but no spatial variability)
- no error covariance information is included: each node assumed independent
- criteria for 5000 draws: high enough to observe power-law decay in error degree variances (i.e. effect of assuming uncorrelated errors attenuates)

Implementation:
 • parallel implementation, using the multiprocessing Python module [11]
 • 3,3 seconds per sliced-layer, per worker, per draw (e.g. 2 hours on 40 workers)
 • random draws are partitioned in 100-draws blocks
 • the variance of g partitions of k draws is consolidated, using the following:

$$\text{Var}(X_1, \dots, X_n) = \frac{k-1}{gk-1} \left(\sum_{i=1}^n v_i + \frac{k(g-1)}{k-1} \text{Var}(E_i) \right)$$
 with E_i, v_i mean and variance of each partition
 → could be easily scaled to more complex, larger schemes

Ideal output: result of unmodelled masses

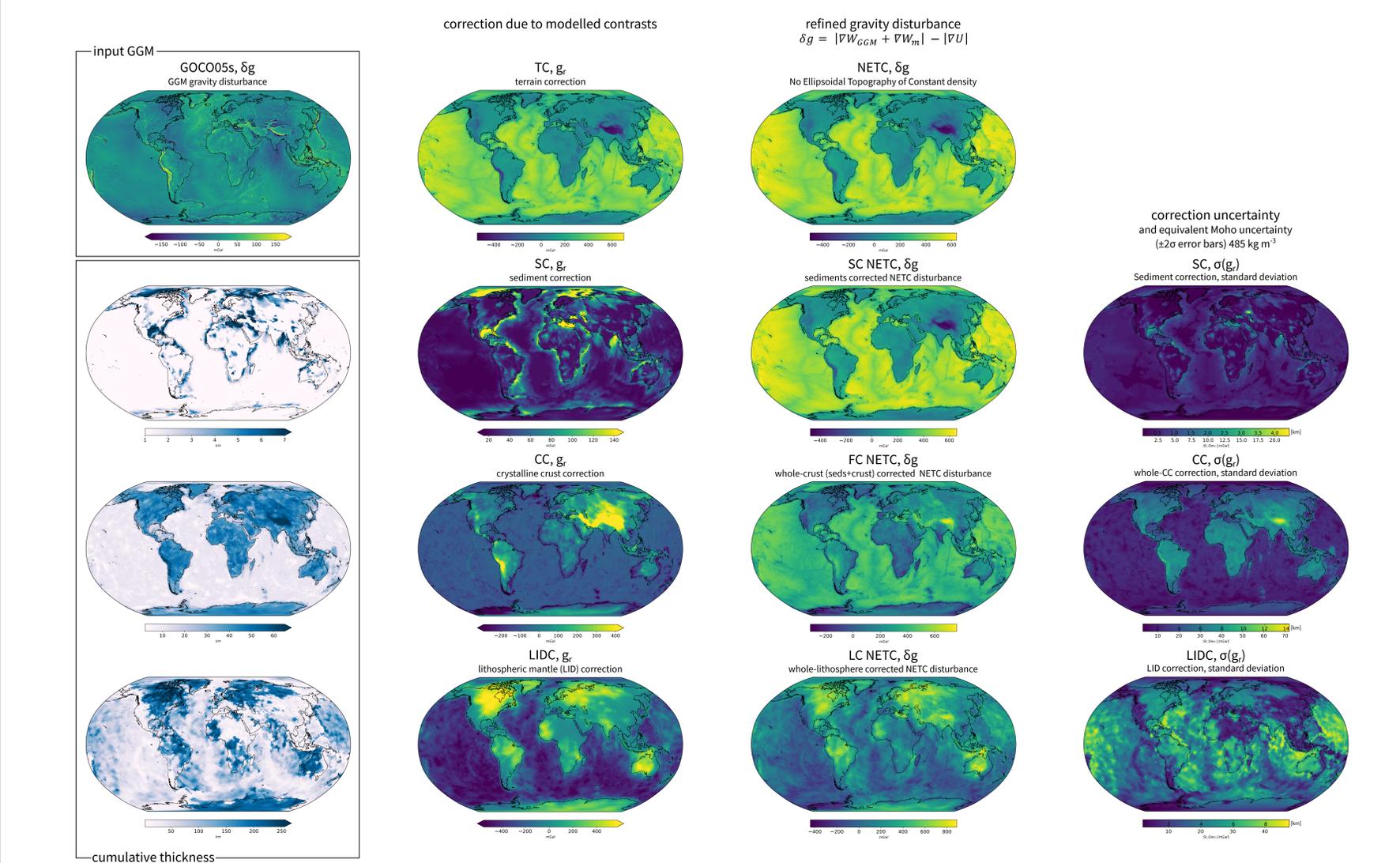


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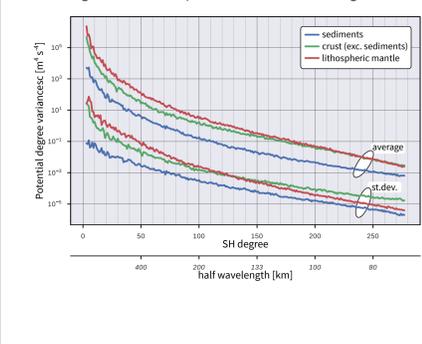
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Results: forward modelled reductions

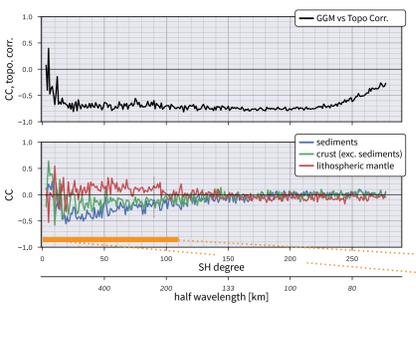
All functionals were computed at 10 km over GRS80, up to SH degree = 280



degree variances spectra: modelled effect against error



correlation coefficients, against GGM



concluding remarks

Correlation coefficients were computed according to Wieczorek [3] formulation. For two SH functions f and g, for a given degree l:

$$CC_{fg}(l) = \frac{S_{fg}(l)}{\sqrt{S_{ff}(l) S_{gg}(l)}}$$
 where S_{ff} , S_{gg} are the power spectra of the functions (degree variance) and S_{fg} is the cross-power spectrum (degree covariance).

$$S_{ff}(l) = \sum_{m=-l}^l f_{lm}^2, S_{gg}(l) = \sum_{m=-l}^l g_{lm}^2, S_{fg}(l) = \sum_{m=-l}^l f_{lm} g_{lm}$$
 CC(l) can possess values between 1 and -1.
 first 120 degrees, zoom

concluding remarks

- Outcome (and collaterals):
 - error estimate of gravity model "after reduction" relying on a layer-based, spectral domain forward modelling of reductions and propagated errors
 - reproduction of "common" and "novel" reductions from a topography-free to an (ideally) lithosphere-free disturbance (albeit with simple assumptions)
- Room for improvement:
 - realistic, data dependent, error estimates e.g. weight according to data density, observable - and error propagation from conversion
 - upper mantle model and velocity conversion integrate available models, removal of lithosphere only shows LAB as artifact compositional model: refine or assess effect of "coarse" assumptions?
 - gravity-model-aware adaptation of reductions truncating at maximum SH degree is not enough e.g. take into account high-degree regularization of sat-only models